

ΠΑΝΕΛΛΑΔΙΚΕΣ ΕΞΕΤΑΣΕΙΣ
Δ' ΤΑΞΗΣ ΕΣΠΕΡΙΝΟΥ ΓΕΝΙΚΟΥ ΛΥΚΕΙΟΥ
ΤΕΤΑΡΤΗ 13 ΙΟΥΝΙΟΥ 2018
ΕΞΕΤΑΖΟΜΕΝΟ ΜΑΘΗΜΑ:
ΦΥΣΙΚΗ ΠΡΟΣΑΝΑΤΟΛΙΣΜΟΥ

ΕΝΔΕΙΚΤΙΚΕΣ ΑΠΑΝΤΗΣΕΙΣ ΘΕΜΑΤΩΝ

ΘΕΜΑ Α

- A1. γ
A2. δ
A3. α
A4. δ
A5. α) Λάθος β) Σωστό γ) Λάθος δ) Σωστό ε) Λάθος

ΘΕΜΑ Β

B1. $d_2 = \sqrt{4\lambda_1^2 + \frac{9\lambda_1^2}{4}} = \sqrt{\frac{25\lambda_1^2}{4}} = \frac{5\lambda_1}{2} = 2,5\lambda_1$

$$d_2 - d_1 = 2,5\lambda_1 - \lambda_1 = \frac{\lambda_1}{2} \quad \text{υδ} = \lambda_1 \cdot f_1 = \lambda_2 \cdot f_2 \rightarrow \lambda_1 \cdot \cancel{f_1} = \lambda_2 \cdot \cancel{f_2} \rightarrow \lambda_2 = \frac{\lambda_1}{2}$$

$$A' = \left| 2A \sin \pi \frac{d_2 - d_1}{\lambda_2} \right| = \left| 2A \sin \pi \frac{\frac{\lambda_1}{2}}{\frac{\lambda_1}{2}} \right| = 2A$$

Επιλέγω (i)

B2. $\Sigma \vec{\tau}_{\text{εξ}} = 0 \rightarrow \vec{L}_1 = \vec{L}_2 \rightarrow m u_1 R = m u_2 \frac{R}{2} \rightarrow u_2 = 2u_1$

$$\begin{aligned} W_F &= K_2 - K_1 = \frac{1}{2} m u_2^2 - \frac{1}{2} m u_1^2 \\ &= \frac{1}{2} m (4u_1^2 - u_1^2) \\ &= \frac{3}{2} m u_1^2 \\ &= \frac{3}{2} m \omega^2 R^2 \end{aligned}$$

Επιλέγω (iii)

B3. $x = u_{\Delta} \cdot t$

$$4h = u_{\Delta} \cdot \sqrt{\frac{2h}{g}} \rightarrow 16h^{\frac{3}{2}} = u_{\Delta}^2 \cdot \frac{2h}{g} \rightarrow u_{\Delta} = \sqrt{8gh}$$

Εξ. συνέχειας:

$$\begin{aligned} \Pi_r &= \Pi_{\Delta} \rightarrow A_r \cdot U_r = A_{\Delta} \cdot U_{\Delta} \rightarrow 2A_{\Delta} \cdot U_r = A_{\Delta} \cdot U_{\Delta} \\ &\rightarrow U_{\Delta} = 2U_r \rightarrow \sqrt{8gh} = 2U_r \\ 8gh &= 4U_r^2 \\ gh &= \frac{U_r^2}{2} \end{aligned}$$

Εξ. Bernoulli:

$$\begin{aligned} P_r + \frac{1}{2}\rho U_r^2 &= P_{\Delta} + \frac{1}{2}\rho U_{\Delta}^2 + \rho gh \\ P_r - P_{\Delta} &= \frac{1}{2}\rho U_{\Delta}^2 - \frac{1}{2}\rho U_r^2 + \rho gh \\ &= \frac{1}{2}\rho 4U_r^2 - \frac{1}{2}\rho U_r^2 + \rho \cdot \frac{U_r^2}{2} \\ &= 2\rho U_r^2 \end{aligned}$$

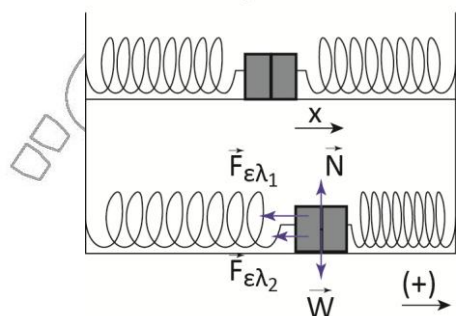
Επιλέγω (i)

ΘΕΜΑ Γ

Γ1.

$$\begin{aligned} \text{ΘΙ: } u_1 &= u_{\max} = \omega_1 \cdot A_1 \\ &= \sqrt{\frac{K_1}{m_1}} \cdot \Delta \ell = 5 \cdot 0,4 = 2 \text{ m/sec} \\ \text{ΑΔΟ } \vec{p}_{\alpha\rho\chi} &= \vec{p}_{\tau\epsilon\lambda} \rightarrow m_1 \cdot u_1 = (m_1 + m_2) \cdot u_2 \\ v_{\Sigma} &= \frac{u_1}{2} = 1 \text{ m/sec} \end{aligned}$$

ΘΙ, ΘΦΜ



Στη Θ.Ι. $\Sigma F = 0$ (Θ.Φ.Μ)

Σε τυχαία θέση που απέχει x από τη Θ.Ι

$$\Sigma F = -F_{ελ_1} - F_{ελ_2}$$

$$\Sigma F = -k_1 \cdot x - k_2 \cdot x$$

$$\Sigma F = -(k_1 + k_2) \cdot x$$

$$\Sigma F = -2k \cdot x$$

Άρα εκτελεί απλή αρμονική ταλάντωση με $D = 2k = 100 \text{ N/m}$.

$$\text{Θ.Ι} \quad V_z = v_{\max} \rightarrow V_z = \omega \cdot A \rightarrow V_z = \sqrt{\frac{D}{m_1 + m_2}} \cdot A \rightarrow A = 0,2 \text{ m}$$

$$\text{Γ2.} \quad D = (m_1 + m_2) \omega^2 \rightarrow \omega = \sqrt{\frac{D}{m_1 + m_2}} = 5 \text{ rad/sec}$$

$$x = A \eta \mu(\omega t + \phi_0) \quad t = 0 \rightarrow x = 0, \quad v > 0$$

$$x = 0,2 \eta \mu(st) \text{ (SI)} \quad \text{Άρα } \phi_0 = 0$$

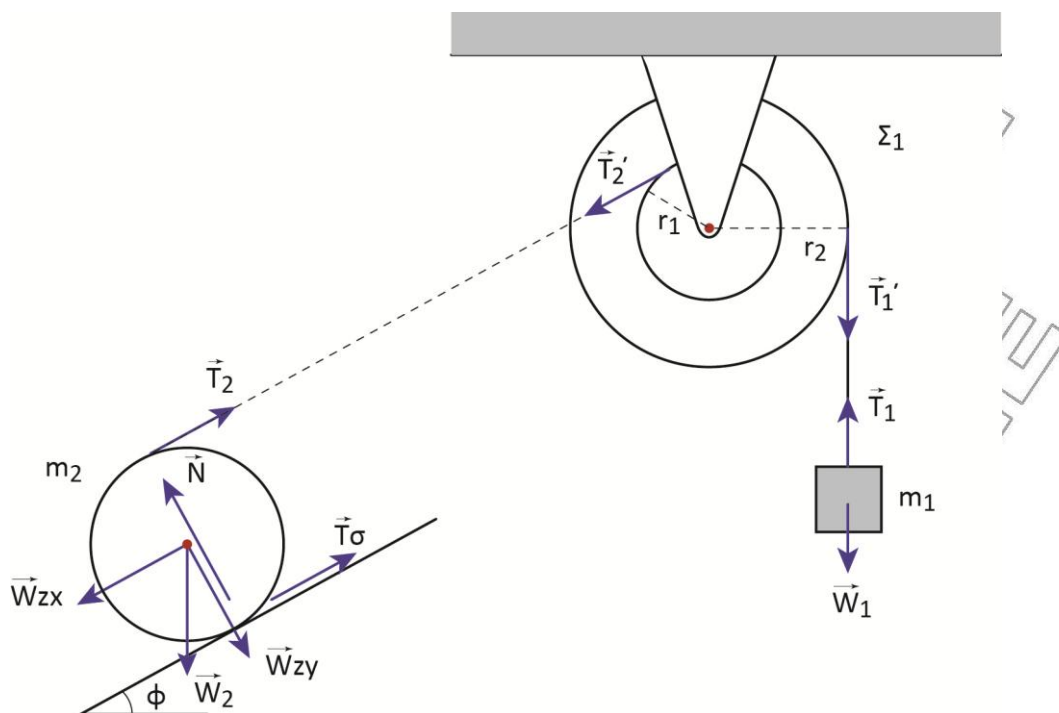
$$\text{Γ3.} \quad \frac{\Delta P}{\Delta t} = \Sigma F = -D \cdot x$$

$$\left| \frac{\Delta P}{\Delta t} \right|_{\max} = D \cdot A$$

$$= 100 \cdot 0,2$$

$$= 20 \text{ kg m/sec}^2$$

ΘΕΜΑ Δ



Δ1. $m_1 \quad \Sigma F = 0 \rightarrow T_1 = W_1 = m_1 g = 30 \text{ N}$

$\Sigma_1 \quad \Sigma \tau = 0 \rightarrow T'_1 \cdot r_2 - T'_2 \cdot r_1 = 0$

$\rightarrow T'_2 = \frac{T'_1}{2} = 15 \text{ N}$

Δ2. $\Sigma F_x = m_2 \cdot \alpha_{cm} \rightarrow W_{2x} - T\sigma = m_2 \cdot \alpha_{cm} \rightarrow m_2 g \sin \phi - T\sigma = m_2 \alpha_{cm} \quad (1)$

$\Sigma \tau = I_{cm} \cdot \alpha_{\gamma\omega\nu} \rightarrow T\sigma \cdot R = \frac{1}{2} m_2 R^2 \cdot \frac{\alpha_{cm}}{R} \quad (2)$

$\xrightarrow{(3)+(4)} m_2 g \sin \phi = \frac{3}{2} m_2 \alpha_{cm} \rightarrow \alpha_{cm} = \frac{2}{3} g \sin \phi = 4 \text{ m/sec}^2$

Δ3. $m_1 \quad \Sigma F = m_1 \cdot \alpha_1 \rightarrow W_1 - T_1 = m_1 \cdot \alpha_1 \quad (3)$

τροχ. $\Sigma \tau = I_{cm} \cdot \alpha_{\gamma\omega\nu} \rightarrow T'_1 \cdot r_2 = I_{cm} \cdot \frac{\alpha_1}{r_2} \rightarrow T'_1 = \frac{I_{cm}}{r_2^2} \cdot \alpha_1 \quad (4)$

$\xrightarrow{(3)+(4)} m_1 g = \left(m_1 + \frac{I_{cm}}{r_2^2} \right) \cdot \alpha_1 \rightarrow 2 \text{ m/sec}^2$

Δ4. $\Delta x_1 = \frac{1}{2} \alpha_1 \cdot t_1^2 \rightarrow t_1 = \sqrt{\frac{2\Delta x_1}{\alpha_1}} \rightarrow t_1 = 0,5 \text{ sec}$

$$v_1 = \alpha_1 \cdot t_1 = 1 \text{ m/sec}$$

$$\omega_1 = \frac{v_1}{r_2} = 5 \text{ rad/sec}, \quad K_{\text{τροχ}(t_1)} = \frac{1}{2} I_{\text{cm}} \cdot \omega^2 = 6 \text{ J}$$

ΚΑΛΑ ΑΠΟΤΕΛΕΣΜΑΤΑ!!!